

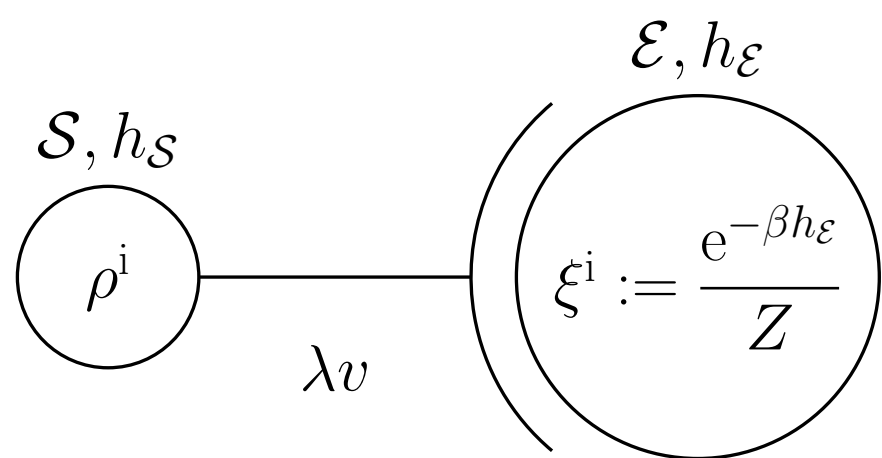
Landauer's Principle in Repeated Interaction Systems

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1. Landauer's Principle

A small system $\mathcal{S}$ interacts with an environment $\mathcal{E}$ for time τ :



This process yields, for $U := \exp(-i\tau(h_S \otimes \text{Id} + \text{Id} \otimes \mathcal{E} + \lambda v))$, final states

$$\rho^f := \text{Tr}_{\mathcal{E}}(U \rho^i \otimes \xi^i U^*), \quad \xi^f := \text{Tr}_{\mathcal{S}}(U \rho^i \otimes \xi^i U^*).$$

Balance equation: $\Delta S_{\mathcal{S}} + \sigma = \beta \Delta Q_{\mathcal{E}}.$

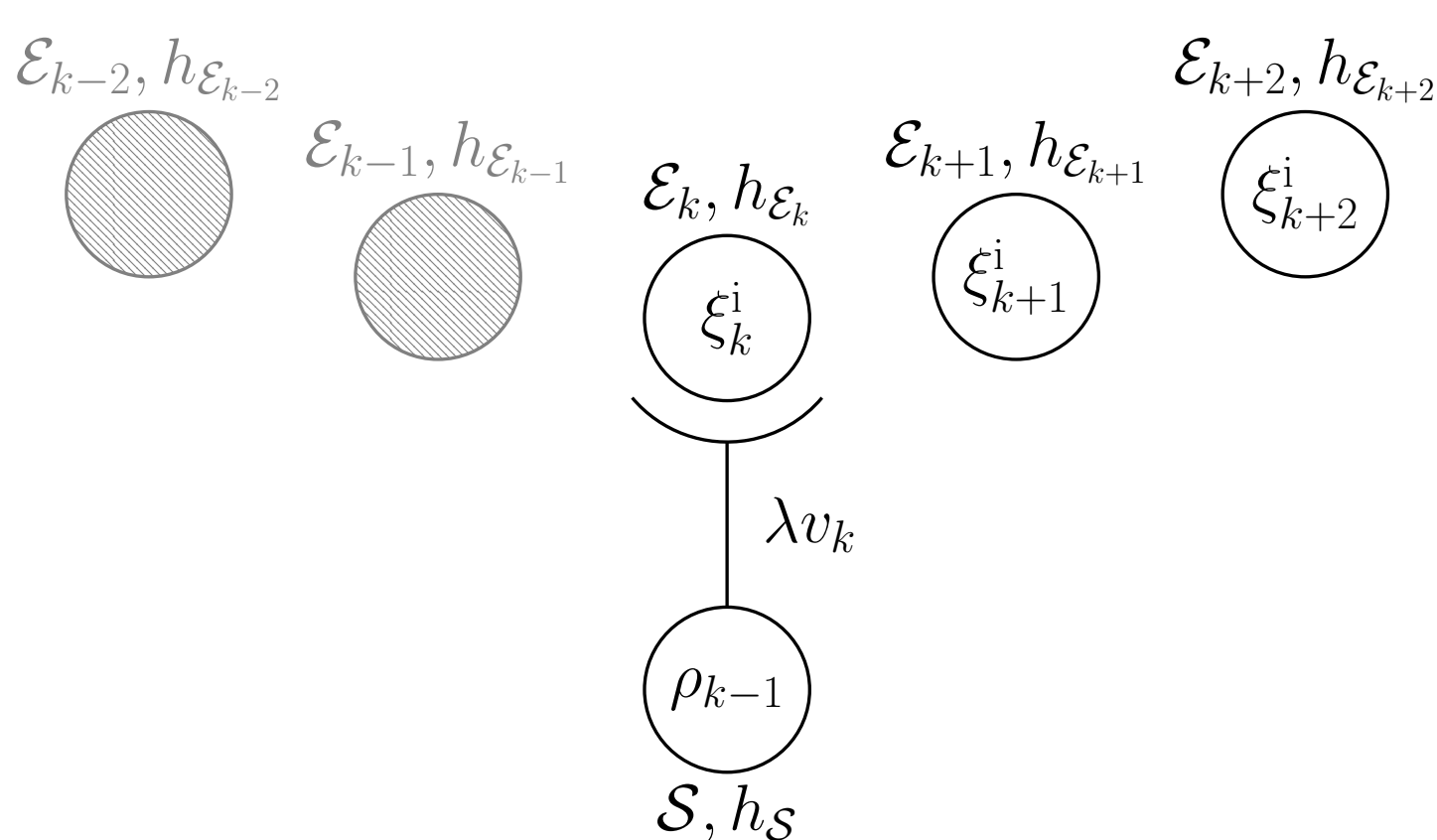
- $\Delta S_{\mathcal{S}} := S(\rho^f) - S(\rho^i)$ is the change in entropy of $\mathcal{S}$, where $S(\eta) := -\text{Tr} \eta \log \eta$.
- $\sigma := S(U \rho^i \otimes \xi^i U^* | \rho^f \otimes \xi^f)$ is the *entropy production*, which we define via the relative entropy, $S(\eta | \chi) := \text{Tr}(\eta(\log \eta - \log \chi)) \geq 0$.
- $\Delta Q_{\mathcal{E}} := \text{Tr}(h_{\mathcal{E}}(\xi^f - \xi^i))$ is the change in energy of $\mathcal{E}$.

The Landauer bound: $\Delta Q_{\mathcal{E}} \geq \beta^{-1} \Delta S_{\mathcal{S}}.$

In particular, the amount of heat exchanged during the erasure of one bit of information is bounded below by $kT \ln 2$.

2. Repeated interaction systems

The system $\mathcal{S}$ interacts with a chain of probes $\mathcal{E}_1, \mathcal{E}_2, \mathcal{E}_3, \dots$



The *reduced dynamics* on $\mathcal{S}$ induced by the interaction with $\mathcal{E}_k$ is

$$\mathcal{L}_k : \mathcal{I}_1(\mathcal{H}_{\mathcal{S}}) \rightarrow \mathcal{I}_1(\mathcal{H}_{\mathcal{S}})$$

$$\eta \mapsto \text{Tr}_{\mathcal{E}}(U_k(\eta \otimes \xi_k^i)U_k^*)$$

where $U_k := \exp(-i\tau(h_S \otimes \text{Id} + \text{Id} \otimes h_{\mathcal{E}_k} + \lambda v_k))$.

Then the state of the system after n steps is $\rho_n = \mathcal{L}_n \mathcal{L}_{n-1} \dots \mathcal{L}_1 \rho^i$.

6. Our answer

Denote by ρ_s^{inv} the unique invariant state for $\mathcal{L}(s)$, and let

$$X(s) := U(s)(\rho_s^{\text{inv}} \otimes \xi_s^i)U(s)^* - \rho_s^{\text{inv}} \otimes \xi_s^i.$$

- If $X(s) = 0$ for all $s \in [0, 1]$, and $\rho^i = \rho_{0,T}^{\text{inv}}$, then $\lim_{T \rightarrow \infty} \sigma_T^{\text{tot}} = 0$.
- If $X(s) = 0$ for all $s \in [0, 1]$, but $\rho^i \neq \rho_{0,T}^{\text{inv}}$, then $\lim_{T \rightarrow \infty} \sigma_T^{\text{tot}} < \infty$, but is possibly non-zero.
- If $\sup_{s \in [0,1]} \|X(s)\|_1 > 0$, then $\sigma_T^{\text{tot}} \rightarrow \infty$ in the limit $T \rightarrow \infty$.

3. The adiabatic limit

We consider an adiabatic parameter $T \gg 1$, and a sequence of T probes whose parameters

$$(\beta_{k,T}, h_{\mathcal{E}_{k,T}}, v_{k,T})_{k=1}^T$$

depend on T as follows.

To choose $\beta_{k,T}$ for example, we fix a C^2 function $[0, 1] \ni s \mapsto \beta(s)$, and define $\beta_{k,T} := \beta(k/T)$. We choose $h_{\mathcal{E}_{k,T}}$ and $v_{k,T}$ in the same manner.

Thus, $\mathcal{L}_{k,T}$, the reduced dynamics for step k when the adiabatic parameter is T , may be obtained as $\mathcal{L}(k/T)$ for a C^2 function $s \mapsto \mathcal{L}(s)$.

Then, as T increases the parameters change more slowly from probe to probe and we consider more probes overall.

4. The problem

Each step of an RIS satisfies a balance equation so that

$$\sum_{k=1}^T \Delta S_{k,T} + \sum_{k=1}^T \sigma_{k,T} = \sum_{k=1}^T \beta_{k,T} \Delta Q_{k,T}.$$

We are interested in the saturation of the bound, and hence in $\sigma_T^{\text{tot}} := \sum_{k=1}^T \sigma_{k,T}$ in the adiabatic limit:

$$\lim_{T \rightarrow \infty} \sigma_T^{\text{tot}} = \lim_{T \rightarrow \infty} \sum_{k=1}^T S(U_k \rho_{k-1,T} \otimes \xi_{k,T}^i U_{k,T}^* | \rho_{k,T} \otimes \xi_{k,T}^i).$$

5. Assumptions

We will consider $\dim \mathcal{H}_{\mathcal{S}}, \dim \mathcal{H}_{\mathcal{E}} < \infty$ and make two assumptions.

We assume $\mathcal{L}(s)$ is irreducible for each $s \in [0, 1]$.

We define $P(s)$ as the spectral projector of $\mathcal{L}(s)$ corresponding to $\text{sp} \mathcal{L}(s) \cap S^1$ and assume

$$\ell := \sup_{s \in [0,1]} \text{spr}[\mathcal{L}(s)(\text{Id} - P(s))] < 1.$$

